



ATR 621

Controller



User manual

Table of contents

1	Safety standards.....	5
2	Model identification	5
3	Technical data.....	5
3.1	Main features.....	5
3.2	Hardware features.....	6
3.3	Software features	6
4	Size and installation	7
5	Electrical wirings	7
5.1	Wiring diagram.....	8
6	Display and keys functions.....	12
6.1	Numeric indicators (display).....	12
6.2	Meaning of Status Lights (led)	12
6.3	Keys.....	13
7	Programming and configuration	13
7.1	Programming (or modifying) cycle data.....	13
7.1.1	Programming of starting setpoint (if enabled).....	14
7.1.2	Programming of the step	14
7.1.3	Programming of the auxiliary output (if configured)	15
7.1.4	End programming	15
8	Cycle start	15
8.1	Start of a cycle and setting of delayed start	15
8.2	Fast advancement during the cycle.....	16
8.3	Simple controller function **.....	16
8.4	Output manual control **	17
9	Programmer functions	17
9.1	Hold function.....	17
9.2	Automatic tuning	17
9.3	Manual tuning.....	17
9.4	Recovery of interrupted cycle	18
9.4.1	Recovery with automatic gradient.....	18
9.4.2	Recovery with recovery gradient	19
9.5	Waiting step end	19
9.6	Heating / Cooling PID	20
9.7	Memory Card (optional)	21
10	Serial communication	22
10.1	Slave.....	22
10.2	Master and remote setpoint	24
11	Loading default values / Reset.....	25
11.1	Configuration for installer.....	25
12	Table of configuration parameters	26
13	Alarm intervention modes.....	37
14	Table of Anomaly Signals.....	39

Sommario

1	Norme di sicurezza	43
2	Identificazione del modello.....	43
3	Dati tecnici	43
3.1	Caratteristiche generali	43
3.2	Caratteristiche hardware	44
3.3	Caratteristiche software	44
4	Dimensioni e installazione	45
5	Collegamenti elettrici.....	45
5.1	Schema di collegamento.....	46
6	Funzione dei visualizzatori e tasti.....	50
6.1	Indicatori numerici (display).....	50
6.2	Significato delle spie di stato (led).....	50
6.3	Tasti	51
7	Programmazione e configurazione	51
7.1	Programmazione (o modifica) dati di un ciclo	51
7.1.1	Programmazione del set point iniziale (se configurato)	52
7.1.2	Programmazione dello step (spezzata / passo).....	52
7.1.3	Programmazione dell'uscita ausiliaria (se configurata)	53
7.1.4	Fine programmazione.....	53
8	Partenza di un ciclo di lavoro.....	53
8.1	Partenza del ciclo e impostazione partenza ritardata	53
8.2	Funzione avanzamento veloce	54
8.3	Funzione regolatore semplice **	54
8.4	Controllo manuale dell'uscita **	55
9	Funzioni del programmatore.....	55
9.1	Funzione Hold	55
9.2	Tuning automatico	55
9.3	Tuning manuale.....	56
9.4	Recupero ciclo interrotto.....	56
9.4.1	Recupero con gradiente automatico.....	56
9.4.2	Recupero con gradiente di recupero.....	57
9.5	Attesa fine step	57
9.6	Funzionamento in doppia azione (caldo-freddo)	58
9.7	Memory Card (opzionale)	60
10	Comunicazione seriale	60
10.1	Slave	60
10.2	Master e setpoint remoto	63
11	Caricamento valori di default.....	63
11.1	Configurazione per installatore.....	64
12	Tabella parametri di configurazione	65
13	Modi d'intervento allarmi	77
14	Tabella segnalazioni anomalie	79

Introduction

Thanks for choosing a Pixsys controller.

With ATR621 model Pixsys integrates in a single device all options for sensors reading and actuators control, beside an useful supply with extended range 24..230 Vac/Vdc. With the analogue universal input and the output configurable as relay or SSR, the user or the retailer can reduce stock needs. The series includes also a model with serial communication RS485 Modbus Rtu and linear output 0-10V, 0/4-20mA. The possibility to repeat parameterization is simplified by the Memory Cards with internal battery that do not require power supply for the controller.

1 Safety standards

Carefully read the instructions and safety measures in this manual before using the device. Disconnect power before performing any interventions on the electrical connections or hardware settings.

Only qualified personnel may use/perform maintenance in full respect of the technical data and declared environmental conditions.

Do not dispose of electrical appliances together with household waste.

In compliance with the European Directive 2002/96/EC, waste electrical equipment must be collected separately for eco-compatible reuse or recycling.

2 Model identification

ATR621 includes 3 versions. Looking at the following table it is possible to find the required model.

Power supply 24..230 Vac/Vdc $\pm 15\%$ 50/60Hz – 5,5VA

ATR621-12ABC	1 Analogue input + 2 relays 8A + 1 SSR + D.I.
---------------------	---

ATR621-14ABC	1 Analogue input + 3 relays 8A + 1 Relays 5A (30V) + D.I.
---------------------	---

ATR621-13ABC-T	1 Analogue input + 3 relays 8A + 1 Output V/mA/SSR + RS485
-----------------------	--

3 Technical data

3.1 Main features

Displays	4 digits display 0,50 inches + 4 digits display 0,30 inches
Operating Temperature	Temperature 0-45°C - Humidity 35..95uR%
Sealing	Front panel IP54, box IP30, terminal blocks IP20
Material	Box: Noryl UL94V1 self-extinguish Front panel: PC ABS UL94V0 self-extinguish
Weight	Approx. 250 g

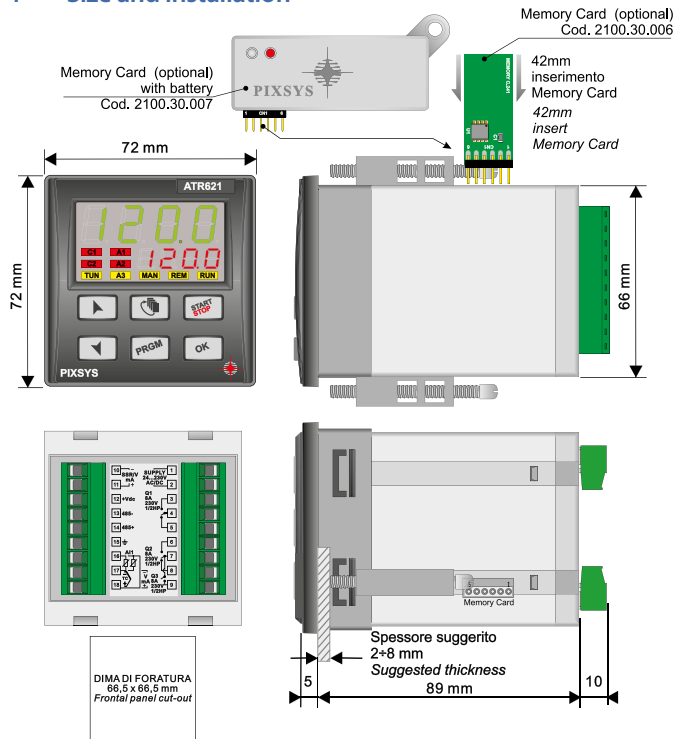
3.2 Hardware features

Analogue inputs	AI1 - Configurable via software Thermocouples: type K,S,R,J,E,N. Automatic compensation of cold junction from 0..50 °C. Thermoresistances: PT100, Input V/mA: 0-10V, 0-20mA, 4-20mA.	Tolerance (25°C) +/-0.2 % ± 1 digit for thermocouple, thermoresistance and V/mA. Cold junction accuracy 0.1°C/°C Impedance: 0-10V: Ri>110KΩ 0-20mA: Ri<5Ω 4-20mA: Ri<5Ω
Relay outputs	Configurable as control and alarm output.	Contacts: - Q1, Q2, Q3: 8A-250V~ for resistive charges - Q4: 5A-30V for resistive charges
Output SSR/ V/ mA	1 SSR /V/mA Selectable as command output, alarm or process/ setpoint retransmission.	Configurable: SSR 12V 30mA 0-10V (9500 points) 0-20mA (7500 points) 4-20mA (6000 points)
Supply	Extended range 24..230Vac/ Vdc ±15% 50/60Hz	Consumption: 5.5VA
UL specifications	Over Voltage Category: II Type 1 Enclosure Pollution Degree: 2 or better Software Class: A	

3.3 Software features

Control algorithms	ON-OFF with hysteresis. P, PI, PID, PD time proportioned.
Proportional band	0...9999°C o °F
Integral time	0,0...999,9 sec (0 excludes)
Derivative time	0,0...999,9 sec (0 excludes)
Controller functions	Manual or automatic tuning, selectable alarms and functions selection by digital input.

4 Size and installation



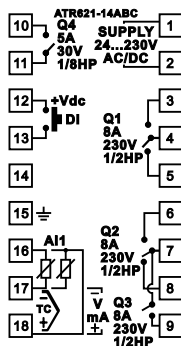
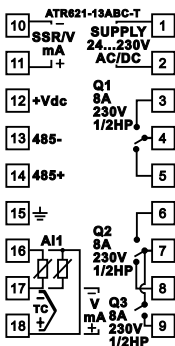
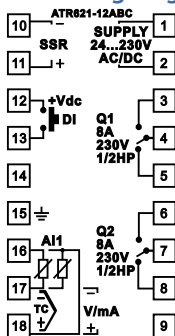
5 Electrical wirings



Although this controller has been designed to resist noises in an industrial environments, please notice the following safety guidelines:

- Separate control lines from the power wires.
- Avoid the proximity of remote control switches, electromagnetic meters, powerful engines.
- Avoid the proximity of power groups, especially those with phase control.

5.1 Wiring diagram

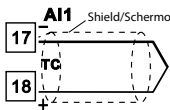


5.1.a Power supply



Switching supply with extended range 24..230 Vac/dc
±15% 50/60Hz – 5,5VA

5.1.b Analogue input AI1

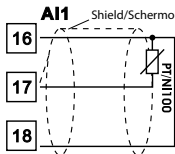


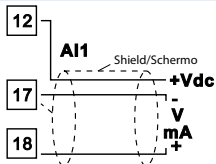
For thermocouples K, S, R, J, E, N.

- Comply with polarity
- For extensions make sure to use the correct extension/compensating cable
- When shielded cable is used, it should be grounded at one side only.

For thermoresistances PT100

- For a three-wires connection use cables with the same diameter.
- For a two-wires connection short-circuit terminals 16 and 18.
- When shielded cable is used, it should be grounded at one side only.

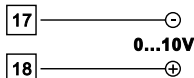




For linear signals Volt/mA

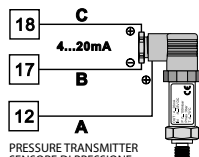
- Comply with polarity
- When shielded cable is used, it should be grounded at one side only.

5.1.c Examples of connection for linear input AI1



For linear signals 0...10V

- Comply with polarity



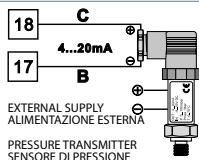
For linear signals 0/4...20mA with three-wires sensors

- Comply with polarity

C = Sensor output

B = Sensor ground

A = Sensor supply (12Vdc/25mA)

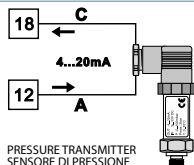


For linear signals 0/4...20mA with external power supply for sensor

- Comply with polarity

C = Sensor output

B = Sensor ground



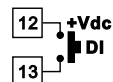
For linear signals 0/4...20mA with two-wires sensors

- Comply with polarity

C = Sensor output

A = Sensor supply (12Vdc/25mA)

5.1.d Digital input (ATR621-12ABC and 14ABC)



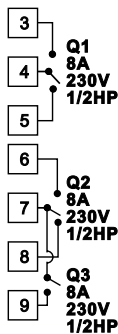
Digital input (parameter d_{DI}).

5.1.e SSR output (ATR621-12ABC and 14ABC)



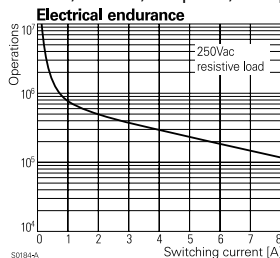
Command output SSR: 12V, 30mA max, SELV, Limited
Energy circuit < 15 W

5.1.f Relay outputs Q1, Q2, Q3



Contacts capacity:

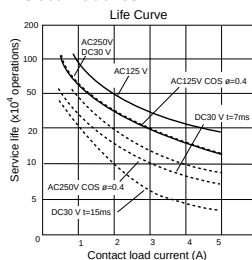
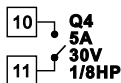
- 8A, 250Vac, resistive charge 10^5 operations.
- 30/3A, 250Vac, $\cos\phi=0.3$, 10^5 operations.



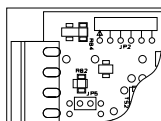
5.1.g Relay outputs Q4 (ATR621-14ABC)

Contacts capacity:

- 5A, 250Vac, resistive charge 18×10^4 operations.
- Class 2 source

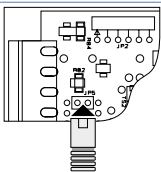


5.1.h Output mA / Volt (ATR621-13ABC-T)



Analogue output in **mA** configurable as command (Parameter `c.out`) or retransmission of process-setpoint (Parameter `rEtr`).

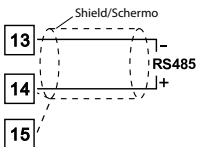
To use analogue output in mA, JP5 has not to be entered.



Analogue output in **Volt** configurable as command (Parameter `c.out`) or retransmission of process-setpoint (Parameter `rEtr`).

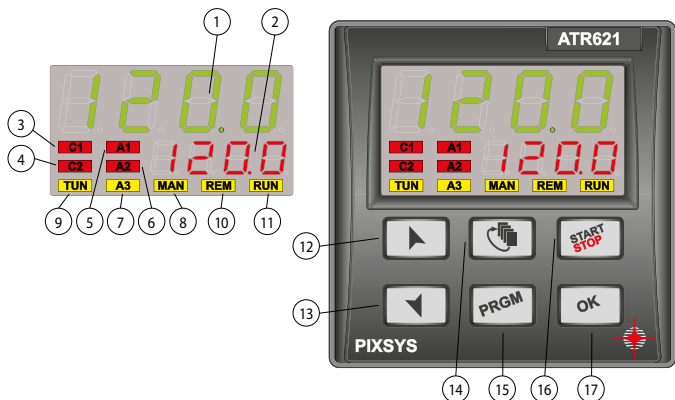
To use analogue output in Volt, enter JP5 as indicated in the figure.

5.1.i Serial input (ATR621-13ABC-T)



Communication RS485 Modbus RTU.

6 Display and keys functions



6.1 Numeric indicators (display)

1	1234	Usually visualizes process value, it may visualize also setpoint value, time elapsed from cycle start, number of operating step or the percentage value of the command output. During configuration it visualizes the value of entering parameter.
2	1234	Visualization can be customized with setpoint, time elapsed from cycle start or number of operating step. During configuration it visualizes the value of entering parameter.

6.2 Meaning of Status Lights (led)

3	C1	On when command output is active. For open /close logic: on during valve opening.
4	C2	For open/ close logic: on during valve closing.
5	A1	On when alarm 1 is active.
6	A2	On when alarm 2 is active.
7	A3	On when alarm 3 is active.
8	MAN	On when Manual function is active
9	TUN	On when controller is executing an auto-tuning cycle.
10	REM	On when serial communication is in progress.
11	RUN	On when controller is operating a cycle or is thermocontrolling.

6.3 Keys

		• In configuration allows to scroll and modify parameters. • Scroll cycles to be started or modified.
12		• In cycle programming allows to modify time and setpoint parameters. • Modifies setpoint in <code>EHET</code> function. • Modifies command output percentage in <code>PRM</code> function. • Allows a quick advancement of the cycle when it is in "START".
13		• In configuration allows to scroll and modify parameters. • Scroll cycles to be started or modified. • In cycle programming allows to modify time and setpoint parameters. • Modifies setpoint in <code>EHET</code> function. • Modifies command output percentage in <code>PRM</code> function. • Allows a quick retrograde of the cycle when it is in "START".
14		• Whit controller in STOP it visualize the duration of the last cycle. • In configuration it assigns a mnemonic code or a number to the selected parameter. • During a cycle it allows to visualize cycling the setpoint and the other data.
15	<code>"PRGM"</code>	• Whit controller in STOP allows to enter cycle modification and configuration. • During a cycle, if pressed for 1 second, it allows to activate/deactivate HOLD function.
16	<code>"START"</code> <code>"STOP"</code>	• Start/Stop a cycle. • In parameter configuration and cycle data modification, it is used as exit key (ESCAPE).
17	<code>"OK"</code>	• Value or selected function confirmation.

7 Programming and configuration

There are two programming levels:

1. **Cycles programming** (for operator/user) means entering time/setpoint values for each step of cycle.
2. **Configuration** (for manufacturer/installer of plant), to enter main parameters (sensor type, output type, auxiliary output intervention type ext.).

7.1 Programming (or modifying) cycle data

With or without starting setpoint and timed auxiliary outputs.

The above specifications underline the possibility given to the installer (plant's manufacturer) to choose the sequence of operations required for the programming of a firing cycle.

This paragraph includes all available options. In case that the installer decides to choose a simplified programming with less options, it is highly recommended to prepare additional instructions specifying only the chosen sequence.

Set the controller in S_{tOP} and follow the points below:

	Press	Display	Do
1	"PRGM"	Red display shows $cY.01$	
2			Decrease or increase to visualize $cY.01$ (for cycle no.1), $cY.02$ (for cycle no.2) up to $cY.15$ (for cycle no.15).

7.1.1 Programming of starting setpoint (if enabled)

This is useful for example when the kiln is still hot and cycle has to start from a lower temperature.

	Press	Display	Do
3	"OK"	Red display shows $00-5$. Green display shows "starting setpoint". Otherwise pass to point 5.	At any time press "START STOP" to exit programming with storing modified data.
4		Increase or decrease value on green display.	Enter starting setpoint (starting temperature)

* The two first digits indicate the number of the step which is being modified. Last digit visualizes t if a step duration time is being entered, S if a setpoint value is being entered (ex: temperature to reach into selected time) and R if the status of the auxiliary output is being entered.

7.1.2 Programming of the step

	Press	Display	Do
5	"OK"	Red display shows $01-t$. Green display shows step time. Increase or decrease value on green display.	Enter step duration in hour: minutes.
6		NB: Each cycle is composed of max. 45 programmable steps, after those it skips automatically to point 12.	NB: Set for endless time or --- for cycle end (if not all steps are used) and skip to point 11.
7	"OK"	Red display shows $01-S$. Green display shows the step setpoint (temperature that has to be reached within given time).	With keys  or  enter setpoint (temperature reached at step end).

7.1.3 Programming of the auxiliary output (if configured)

	Press	Display	Do
8	"OK"	Red display shows $\square I-R$. Green display shows $R1.0F$ or $R1.0n$.	If $R1.1$ is not programmed as auxiliary time ($R1.0.r.5$) skip to point 10.
9			Set auxiliary output status during the step: $R1.0n$ for active output and $R1.0F$ for not active output.
10	"OK"	If $R1.2, R1.3$ are programmed as time auxiliary go back to point 9. Green display will visualize the number and the status of the selected auxiliary ($R2.0F/ R2.0n, R3.0F/ R3.0n$). Once selected all auxiliary go back to point 5.	

7.1.4 End programming

	Press	Display	Do
11	"OK"	Controller returns in STOP mode saving the cycle. Red display shows $StoP$.	If $R1.1, R1.2, R1.3$ are selected as auxiliary ($R1.0.r.5$) repeat the procedure of points 9 and 10 for the output status at cycle end.

8 Cycle start

8.1 Start of a cycle and setting of delayed start

Red display shows $StoP$.

	Press	Display	Do
1	"START" "STOP"	Red display shows cycle selection.	
2			Decrease or Increase until chosen cycle is visualized $cY.01$ (for cycle no.1), $cY.02$ (for cycle no.2),
3	"OK" or "START" "STOP"	Cycle starts. Buzzer sounds for a second. Green display shows the process while red display shows the setpoint introduced on parameter $29 u.1.d.2$.	

If function "Delayed start" is enabled (see parameter 30 *dESt*) follow the points below:

	Press	Display	Do
4	"OK" or "START" "STOP"	Red display shows <i>URt</i> while green display shows the programmed waiting time flashing.	
5	"^" "v"	Increase or decrease time for delayed start (hours:minutes).	
6	"OK"	Start of waiting time. At elapsing of programmed time, cycle will start.	Press "^" or "v" to modify the time.

8.2 Fast advancement during the cycle

During functioning or after a restart it can be useful to scroll onwards or backwards the cycle in progress, to reach chosen setpoint value.

	Press	Display	Do
1	"^" "v"	Forwards or backwards (each beep of internal buzzer means one minute).	To stop the cycle and set the controller in , before cycle end press "START STOP" for a second.

8.3 Simple controller function **

StoP controller.

	Press	Display	Do
1	"START" "STOP"	Red display shows selected cycle.	
2	"^" "OK"		Increase until visualize <i>tHEr</i> .
3	or "START" "STOP"	Red display shows <i>SPu</i> while green display shows the setpoint.	
4	"^" "v"	Increase or decrease setpoint value.	Enter chosen setpoint value.
5	"OK"	Controller modulates the command output to keep the programmed temperature.	
6	"CE"	Visualize controller values cycling.	To modify setpoint <i>SPu</i> press "CE" and/or arrow keys. To exit, press "START STOP" for a second.

8.4 Output manual control **

This function allows to modify manually the command output, excluding the process control. Output will activate in percentage from 0 to 100% according to time base set on parameter 23 $t.c.$ (cycle time) or on parameter 43 $uRL.t.$ if parameter 1 $c.out$ is set on $c.uRL$. SP controller and follow the table below.

Press	Display	Do
1 "START" "STOP"	Red display shows cycle selection.	
2 "▲"		Increase until visualize PRn .
3 "OK"	Green display shows the process. Red display shows $P.---$, where the output percentage value is visualized. Controller starts to modulate the command output.	To modify percentage pres "▲" or "▼". To esc press "START STOP" for a second.

** Access to this function have to be enabled on parameter 32 $SPFu$.

9 Programmer functions

9.1 Hold function

This function allows to interrupt the cycle: red display visualizes $Hold$ and cycle advancement is stopped. By pressing "▲" or "▼" it is also possible to modify the setpoint.

There are two possibilities to start this function:

- By keyboard: set En on parameter 33 $HLd.F$.
Press "PRGM" for a second: function will be started or stopped.
- By digital input: select $Hold$ on parameter 27 $dGE.i.$ (only for ATR621-12ABC e 14ABC).

NB: It is not possible to enable Hold function by parameter 33 $HLd.F$ if parameter 27 $dGE.i.$ has already been set on $Hold$.

9.2 Automatic tuning

Automatic tuning procedure has been conceived to give user the possibility to have a clear regulation also without knowledge of PID regulation algorithm. Setting $Autd$ on parameter 11 $t.unE$, the controller will check process oscillations and will modify PID parameters if the difference between process and setpoint values is greater than value on P-13 $PG.t.u$. **Parameters 13 $PG.t.u$, 14 $PI.n.P.b.$, 15 $PD.P.b.$ and 16 $PI.n.i.t.$ can be modified entering the dedicated password 5678.**

9.3 Manual tuning

Manual tuning procedure allows user a greater flexibility on deciding to update PID parameters. To enable this function set PRn on parameter 11 $t.unE$.

To start manual tuning procedure, follow the table below:

Press	Display
1 "⏮"	Press until red display shows <code>EUnE</code> .
2 "⏮"	Green display shows <code>on</code> , led TUN turns on and procedure starts.

Controller activates output increasing (or decreasing - if cooling regulation) the process value entered on parameter 12 `5.d.t.u.` Then it turns off the output and calculates the new PID parameters depending on overshoot/undershoot oscillations. It is possible to end manual tuning procedure any time, following the points below:

Press	Display
1 "⏮"	Press until red display shows <code>EUnE</code> .
2 "⏮"	Green display shows <code>off</code> , led TUN turns off and procedure ends. PID parameters will not be modified.

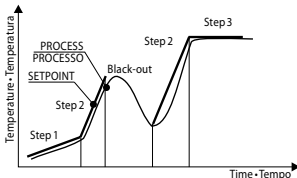
9.4 Recovery of interrupted cycle

Recovery function is particularly useful for kilns temperature regulation. After a power failure, at restarting ATR621 can resume the interrupted cycle. There are two recovery modes.

9.4.1 Recovery with automatic gradient

To enable cycle recovery with automatic gradient, set 1 on parameter 38 as `r.t.c.y`. This mode does not operate for cooling regulations. At restart, after a power failure, controller will operate like this:

1. If a power failure occurs during a rising step, the gradient will be same as the operating step (setpoint temperature equal to the temperature read by the sensor).
2. If a power failure occurs during a holding step, two options are possible. If gap between process and setpoint is limited (not exceeding the value on parameter 37 `h.g.s.e`) cycle will resume from the point of interruption; if the gap is bigger but controller has not yet executed a cooling step, the cycle will go back to the closest rising step and will repeat the procedure as explained on point 1.
3. If a power failure occurs during a cooling step or a holding step (dwell) after that a cooling step has already been completed, the setpoint will match the the temperature read by the sensor, without including any rising and even skipping to next step if necessary (this a safety tip particularly for glass working).

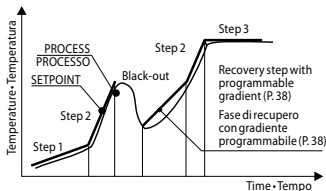


NB: After a power-off the chronometer will restart from 00:00.

9.4.2 Recovery with recovery gradient

To enable cycle recovery with a recovery gradient, enter on parameter 38 *r. i. c. y.* a value (degrees/hour if temperature) greater than 1. At restarting if the kiln temperature (process) is lower than the setpoint, ATR621 locks the working cycle executing a step with the rising gradient set on parameter 38 *r. i. c. y.* to return to the setpoint value entered before the power failure and the cycle restarts from that point.

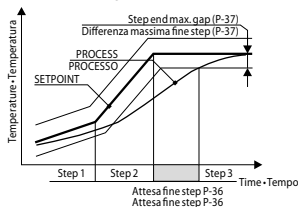
In recovery mode the point on the right of the red display flashes and display shows *r. E. c.* instead of the cycle number.



- Recovery will start only for holding steps or rising steps in heating regulation or for falling steps in cooling regulation.
- To exit manually from recovery mode press “ $\wedge$ ” or “ $\vee$ ”.

9.5 Waiting step end

This function has been conceived to control kilns working cycles, whenever the kiln cannot follow gradients programmed by the user. If at step end the difference between process and setpoint values is greater than the value on parameter 37, controller starts with the next step only after waiting for the time programmed on parameter 36 *U. E. S. E.*, or when this gap becomes lower than parameter 37 *P. G. S. E.*.



- To exit manually from step end waiting function press “ $\wedge$ ”.
- To disable this function fix at 0 end step waiting time *U. E. S. E.*
- During end step waiting red display shows *U. R. i. E.*

9.6 Heating / Cooling PID

ATR621 is suitable also for applications requiring a combined heating-cooling P.I.D. action.

Command output has to be configured as heating PID ($A_{CT.E.} = HEAT$ and $P.b.$ greater than 0), and one of alarms ($AL.1$, $AL.2$, $AL.3$) has to be configured as $COOL$. Command output must be connected to actuator responsible for heating action, while alarm will control the cooling action.

Parameters to configure for heating PID are:

$A_{CT.E.} = HEAT$ Command output action type (Heating)

$P.b.$: Proportional band heating

$t.i.$: Integral time Heating and cooling

$t.d.$: Derivative time Heating and cooling

$t.c.$: Cycle time Heating

Parameters to configure for cooling PID are (example: action associated to alarm 1):

$AL.1 = COOL$ Alarm1 selection (Cooling)

$P.b.\Pi.$: Proportional band multiplier

$ou.d.b.$: Overlapping / Dead band

$ca.c.t.$: Cycle time Cooling

Parameter $P.b.\Pi.$ (that ranges from 1.00 to 5.00) determinates the proportional band for cooling action, according to the formula:

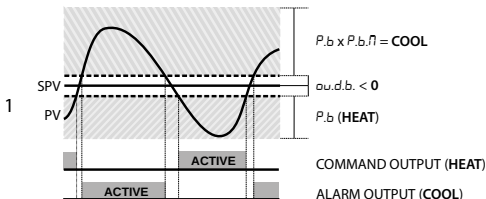
- **Proportional band for cooling action:** $= P.b. * P.b.\Pi.$

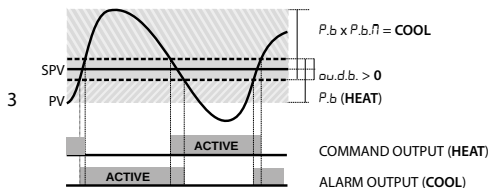
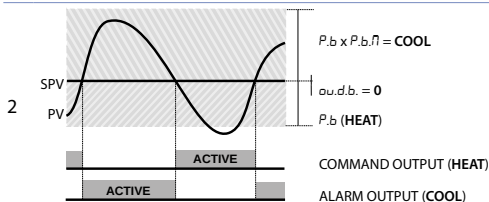
In this way it is possible to have a proportional band for cooling action that will be equal to heating proportional band if $P.b.\Pi. = 1.00$, or 5 times greater if $P.b.\Pi. = 5.00$.

- **Integral and Derivative time** are the same for both actions.

Parameter $ou.d.b.$ establishes the overlapping (in percentage) between the two actions. For installations where heating and cooling outputs cannot be activated at the same time, a Dead band will be configured ($ou.d.b. \leq 0$), viceversa an overlapping will be configured ($ou.d.b. > 0$).

Figure below shows an example of double action PID (heating-cooling) with $t.i. = 0$ and $t.d. = 0$.





Parameter $c.o.c.t.$ has the same meaning of cycle time for heating action $t.c.$.
 Parameter $c.o.o.F.$ (Cooling Fluid) pre-selects the proportional band multiplier and the cooling P.I.D. cycle time $P.b.\bar{n}$, according to cooling fluid type.

$c.o.o.F.$	Cooling fluid type	$P.b.\bar{n}$	$c.o.c.t.$
Air	Air	1.00	10
Oil	Oil	1.25	4
H ₂ O	Water	2.50	2

Once parameter $c.o.o.F.$ has been selected, parameters $P.b.\bar{n}$ / $o.u.d.b.$ and $c.o.c.t.$ can be however modified.

9.7 Memory Card (optional)

Parameters and setpoint values can be easily copied from one controller to others using the Memory Card. Two modes are available:

- With the controller connected to the power supply:**

Insert Memory card when the controller is off.

At switch-on green display shows $\bar{n}E\bar{n}$ and red display shows ---- (only if correct values are stored on Memory). Pressing " $\wedge$ " red display visualizes $LdRd$. Confirm with "OK". Controller loads news values and restarts.

- With the controller not connected to the power supply:**

The memory card is equipped with an internal battery with an autonomy of about 1000 uses. Insert the memory card and press the programming button. When writing the parameters, led turns red and on completing the procedure it turns to green. It is possible to repeat the procedure without any particular attention.

Updating Memory Card

To update the memory card values, follow the procedure described in the first method, setting ---- on red display so as not to load the parameters on controller¹. Enter configuration and change at least one parameter. Exit configuration. Changes are saved automatically.

10 Serial communication

ATR621-13ABC-T is provided with isolated RS485 serial and can receive/transmit data via MODBUS RTU protocol. Device can be configured as master or slave.

Modbus RTU protocol features

Baud-rate	Selectable by parameter 78 <i>b d . r t</i> .	
	4.8 <i>t</i> 4800 bit/sec	9.6 <i>t</i> 9600bit/sec
	19.2 <i>t</i> 19200bit/sec	28.8 <i>t</i> 28800bit/sec
	57.6 <i>t</i> 57600bit/sec	115.2 <i>t</i> 115200bit/sec
Format	Selectable by parameter 79 <i>S E . P . S</i> .	
	8.0 <i>t</i>	8 data bits, no parity, 1 stop bit.
	8.o <i>t</i>	8 data bits, odd parity, 1 stop bit.
	8.E <i>t</i>	8 data bits, even parity, 1 stop bit.
Supported functions	WORD READING (max 20 word) (0x03, 0x04)	
	SINGLE WORD WRITING (0x06)	
	MULTIPLE WORDS WRITING (max 20 word) (0x10)	

10.1 Slave

ATR621-13ABC-T can operate as slave unit setting *d i s* on parameter 77 *r E n . S*: this function allows to control multiple controllers connected to a supervisory system. Each instrument will answer to a Master query only if it contains same address as on parameter 80 *S L . A d*. Allowed addresses are 1 to 254 and there should not be controllers with the same address on the same line. Address 255 can be used by the Master to communicate with all connected devices without knowing their addresses (broadcast mode), while with address 0 all devices receive command, but no answer is expected. ATR621 can introduce an answer delay (in milliseconds) to Master request. This delay has to be set on parameter 81 *S E . d E*. At each parameters modification, instrument stores values in EEPROM memory (100000 writing cycles). **NB:** Modifications made to Words different from those described in the following table can lead to instrument malfunction.

Here below list of available addresses

RO = Read Only	R/W = Read / Write	WO = Write Only
----------------	--------------------	-----------------

¹ If at starting controller shows *Π E Π 0* it means that no data are stored into the Memory Card, however values can be update.

Modbus address	Description	Read Write	Reset value
0	Device type	RO	220
1	Software version	RO	FLASH
5	Slave address	R/W	EEPROM
6	Boot version	RO	FLASH
50	Automatic addressing	WO	-
51	Installation code comparison	WO	-
	Loading Default values:		
500	9999 restore all values except for cycles 9989 restore all values, cycles included	RW	0
900	AI1 process (degrees with tenths of degree for temperature sensors; digits for linear sensors).	RO	-
901	AI2 process (feedback potentiometer-Ohm/10)	RO	-
902	Valve position – 0..100.	RO	-
1000	Process (degrees with tenths of degree for temperature sensors; digits for linear sensors).	RO	-
1001	Process with decimal point selection.	RO	-
1002	Setpoint (with gradient)	RO	0
1003	Setpoint with process decimal point selection	RO	0
1004	Digital input status 0 = input OFF 1 = input ON	RO	0
	Relay status (0=off, 1=on)		
1005	Bit 0 = relay Q4/SSR Bit 1 = relay Q1 Bit 2 = relay Q2 Bit 3 = relay Q3	RO	0
1006	Heating output percentage (0-10000)	RO	0
1007	Cooling output percentage (0-10000)	RO	0
1008	Heating output percentage (0-1000)	RO	0
1009	Cooling output percentage (0-1000)	RO	0
1010	Heating output percentage (0-100)		0
1011	Cooling output percentage (0-100)	RO	0
1012	Alarms status (0=none, 1=active) Bit0 = Alarm 1 Bit1 = Alarm 2 Bit2 = Alarm 3	RO	0
	Error flags		
	Bit0 = Eeprom writing error		
	Bit1 = Eeprom reading error		
	Bit2 = Cold junction error		
1013	Bit3 = Error AI1 (sensor 1) Bit5 = Generic error Bit6 = Hardware error Bit7 = Missing calibration error Bit8 = Eeprom cycle reading error	RO	0
1014	Cold junction temperature (degrees with tenth)	RO	-

Modbus address	Description	Read Write	Reset value
1200	Cycle selection for remote start 1 = cycle1 (...) 15 = cycle15 16 = controller 17 = output manual control	R/W	1
1201	Remote Start/Stop (0 = STOP, 1 = START)	R/W	0
1202	Remote setpoint for controller (degrees with tenths of degree for temperature sensors; digits for linear sensors).	R/W	0
1203	Remote setpoint for controller with process decimal point selection.	R/W	0
1204	Remote manual control output percentage (0-100)	R/W	0
1205	Remote manual control output percentage (0-1000)	R/W	0
1206	Remote manual control output percentage (0-10000)	R/W	0
1207	Manual tuning ON/OFF 0 = Tuning off 1 = Tuning on	R/W	0
1210	OFF LINE time* (milliseconds)	R/W	0
2001	Parameter 1	R/W	EEPROM
...	...	R/W	EEPROM
2100	Parameter 100	R/W	EEPROM
4001	Parameter 1**	R/W	EEPROM
...	...	R/W	EEPROM
4100	Parameter 100	R/W	EEPROM

* If it is 0, control is disabled. If it is different from 0, it is "maximum time that can elapse between two pollings before the controller goes off-line". If it goes Off-line, the controller goes to Stop mode.

** Parameters changed using serial address from 4001 to 4100 are saved in eeprom only after 10" after the last writing of parameters.

10.2 Master and remote setpoint

ATR621-13ABC-T includes a simplified Master mode allowing operation with other programmers ATR621-13ABC-T or with controllers ATR401-22ABC-T.

Setting **SLAVE** on parameter **77 rEN.5**, controller transmits in broadcast (address 0) its status (start/stop) and the control setpoint.

Following table shows all data:

Modbus Address	Description
5000	Controllers status: 0 = Controller in stop 1 = Controller during initial waiting 2 = Controller in start
5001	Remote Setpoint

Setting **SLAVE** on parameter **77 rEN.5**, controller is normally in stop mode; it goes in start when the master device on the serial line starts a cycle.

11 Loading default values / Reset

This procedure allows to restore all default settings.

	Press	Display	Do
1	"PRGM"	Red display shows cycle selection.	
2	"^"		Increase until <i>CONF</i> is visualized.
3	"OK"	Green display shows 0000 with 1st digit flashing, while red display shows <i>PASS</i> .	
4	"^" + "OK"	Flashing digit on green display changes.	Enter password 9999.
5	"OK"	Device loads default settings.	

Entering password 9999 all default parameters will be loaded. If it is necessary to cancel and reset also the cycles, enter password 9989.

11.1 Configuration for installer

To accede configuration parameters it is necessary to *STOP* the controller.

	Press	Display	Do
1	"PRGM"	Red display shows cycle selection.	
2	"^"		Increase until visualize <i>CONF</i> .
3	"OK"	On green display appears 0000 with 1st digit flashing, while red display shows <i>PASS</i> .	
4	"^" + "OK"	Flashing digit of green display changes.	Enter password 1234.
5	"OK"	Green display shows the first parameter while red display shows the value.	
6	"OK"	Allows to switch from mnemonic to numeric parameter visualization (and vice versa).	
7	"^"	Scroll parameters.	Visualize parameter to be modify.
8	"OK"	Allows parameter modification: on red display the chosen parameter value starts flashing.	
9	"^"	Increase or decrease visualized value.	Enter new data.
10	"OK"	Confirms data entering (red display stops flashing).	To modify a new parameter back to point 7.

	Press	Display	Do
11	"START" "STOP"	Configuration ends. Controller is in <i>StoP</i> . NB: If a memory card is introduced, in a few minutes it will be updated according to the modifications done.	

12 Table of configuration parameters

1 *c.out* Command Output

Command output type selection.

c. ol > **Default** (Default parameter).

c.uRL

c.SSr

c.4.20

c.0.20

c.0.10

ATR621 - 12ABC			
	Command	Alarm 1	Alarm 2
<i>c. ol</i>	Q1	Q2	SSR
<i>c.uRL</i>	Q1 (open) - Q2 (close)	SSR	-
<i>c.SSr</i>	SSR	Q1	Q2

ATR621 - 14ABC				
	Command	Alarm 1	Alarm 2	Alarm 3
c. ol	Q1	Q2	Q3	Q4
c.uRL	Q2 (open) - Q3 (close)	Q1	Q4	-

ATR621 - 13ABC-T				
	Command	Alarm 1	Alarm 2	Alarm 3
c. ol	Q1	Q2	Q3	SSR
c.uRL	Q2 (open) - Q3 (close)	Q1	SSR	-
c.SSr	SSR	Q1	Q2	Q3
c.4.20	4...20mA	Q1	Q2	Q3
c.0.20	0...20mA	Q1	Q2	Q3
c.0.10	0...10V	Q1	Q2	Q3

2 *SEn* Sensor

Analogue input 1 configuration.

t.c. t Tc-K: -260..1360°C >**Default**

t.c. S Tc-S: -40..1760°C

t.c. r Tc-R: -40..1760°C

t.c. J Tc-J: -200..980°C

t.c. E Tc-E: -260..740°C

t.c. n Tc-N: -260..1280°C

Pt PT100: -200..600°C

0-10 0..10Volt

0-20	0..20mA
4-20	4..20mA
SP _u	Setpoint (setpoint value is visualized as process)

3 d.P. Decimal Point

Selects type of visualized decimal point.

0 > **Default**

0.0

0.00

0.000

4 LoL.i. Lower Linear Input

AI1 lower limit range, only for linear.

-999..+9999 [digit²]. **Default:** 0.

5 u.P.L.i. Upper Linear Input

AI1 upper limit range, only for linear.

-999..+9999 [digit²]. **Default:** 1000.

6 o.cAL. Offset Calibration

Offset calibration. Number added to visualized process (normally it corrects ambient temperature value).

-999..+1000 [digit²]. **Default:** 0.0.

7 G.cAL. Gain Calibration

Gain calibration. Number multiplied with process value to calibrate working point.

-99.9%..+100.0%. **Default:** 0.0.

8 LoL.S. Lower Limit Setpoint

Setpoint lower limit.

-999..+9999 [digit²] (degrees.tenths for temperature sensors). **Default:** 0.

9 u.P.L.S. Upper Limit Setpoint

Setpoint upper limit.

-999..+9999 [digit²] (degrees.tenths for temperature sensors). **Default:** 1750.

10 dEGr. Degree

Select degree type.

°C Centigrade. > **Default.**

°F Fahrenheit.

11 **TUNE** Tune

Select autotuning type.

DIS. Disabled. > **Default.**

AUTO Automatic. Controller checks constantly the process value and modifies P.I.D. values (if necessary).

MAN. Manual. Started by keys or digital input.

12 **SD.TU.** Setpoint Deviation Tune

Selects deviation from command setpoint as threshold used by manual tuning to calculate P.I.D. parameters.

0..5000 [digit²] (degrees.tenths for temperature sensors). > **Default:** 5.0.

13 **MG.TU.** Max Gap Tune (password 5678)

Selects the max. process-setpoint gap, beyond which the automatic tune recalculates P.I.D. parameters.

1..500 [digit⁴] (degrees.tenths for temperature sensors). > **Default:** 1.0.

14 **MP.B.** Minimum Proportional Band (password 5678)

Selects proportional band min. value selectable by automatic tune.

0..9999 [digit²] (degrees.tenths for temperature sensors). > **Default:** 5.0.

15 **MA.P.B.** Maximum Proportional Band (password 5678)

Selects proportional band max. value selectable by automatic tune.

0..9999 [digit⁴] (degrees.tenths for temperature sensors). > **Default:** 50.0.

16 **MI.IT.** Minimum Integral Time (password 5678)

Selects integral time min. value selectable by automatic tune.

0..999.9 seconds. > **Default:** 10.0.

18 **CACT.** Command Action Type

Command output regulation type.

HEAT (Heat). Heating regulation (n.o.). > **Default**

COOL (Cool). Cooling regulation (n.c.).

19 **CH.** Command Hysteresis

Hysteresis in ON/OFF or dead band in P.I.D. for command output.

-999..+999 [digit²] (degrees.tenths for temperature sensors). > **Default:** 1.0

20 **P.B.** Proportional Band

Process inertia in units (Ex: if temperature in °C)

0 ON/OFF if also **MI.** equal to 0. > **Default.**

1..9999 [digit²] (degrees.tenths for temperature sensors).

21 **I.T.** Integral Time

Integral time. Process inertia in seconds.

0.0..999.9 seconds. 0 disabled integral. > **Default:** 0.0.

22 **D.T.** Derivative Time

Derivative time. Normally ¼ of integral time.

0.0..999.9 seconds. 0 disabled integral. > **Default:** 0.0.

23 **C.C.** Cycle Time

Cycle time (for P.I.D. on contactor 10"/15", for P.I.D. on SSR 1"). For time-proportioned valves see Parameter 43.

1..300 seconds. > **Default:** 10.

24 **L.L.O.P.** Lower Limit Output Percentage

Selects min. value for command output percentage.

0..100% > **Default:** 0%.

25 **U.L.O.P.** Upper Limit Output Percentage

Selects max. value for command output percentage.

0..100% > **Default:** 100%.

26 **C. S.E.** Command State Error

Contact status for command output in case of error.

o.c. (Open Contact) > **Default**

c.c. (Contact closed).

27 **DIGIT. I.** Digital Input

Digital input functioning.

d.i.s. (Disabled). > **Default.**

o.P.E.n Temporary regulation lock input (holding cycle, **o.P.E.n** on display and command output switching off).

E.n.r.g. (Emergency) Emergency input: device stops. It visualizes **E.n.r.g.** with active buzzer until pressing OK.

H.o.l.d Cycle pause with setpoint modifiable by keyboard.

r.c.y.1 (Run Cycle 1) active **RUN** input: cycle 1 starts

r.c.y.2 (Run Cycle 2) active **RUN** input: cycle 2 starts

r.c.y.3 (Run Cycle 3) active **RUN** input: cycle 3 starts

r.c.y.4 (Run Cycle 4) active **RUN** input: cycle 4 starts

r.c.y.5 (Run Cycle 5) active **RUN** input: cycle 5 starts

r.L.c.y (Run Last Cycle) active **RUN** input: starts the last cycle done

r.t.H.E. (Run Thermoregulator) active **RUN** input: thermoregulator function starts

r.M.A.n. (Run Manual) active **RUN** input: manual mode starts

t.u.n.E Input for manual autotuning function

S.t.E.P Pulse input, one step progress with cycle in START

n.E.c.y. Pulse input, skip to the next cycle

28 d.i.c.t. Digital Input Contact Type:

- d.c. (Open Contact)
- c.c. (Contact closed) > **Default**

29 u.i.d.2 Visualization Display 2

Set visualization on display 2 during a cycle.

- E.St.S. (End Step Setpoint) Operating step end temperature
- r.SP.u (Real Setpoint) Updated according to the selected gradient
- c.Y.n.u. (Cycle Number) Number of operating cycle. > **Default.**
- St.n.u. (Step Number) Number of operating step
- t.i.n.E Time elapsed from cycle start
- o.u.t.P. (Output Percentage)

30 d.E.St. Delaied Start

Enables initial waiting for delayed start of cycle.

- d.i.S. (Disabled) Initial waiting disabled. > **Default.**
- E.n. (Enabled) Initial waiting selectable by the user.

31 S.SP.u Starting Setpoint

Enables cycle starting setpoint to guarantee the programmed gradient for the first step.

- d.i.S. (Disabled) Cycle starting setpoint disabled. > **Default.**
- E.n. (Enabled) Cycle starting setpoint selectable by the user.
- E.n.A.t. (Enabled Ambient Temperature) Fixed cycle starting setpoint (25°C for temperature sensors and 0 for linear sensors).

32 SP.F.u. Special Functions

Enables simple thermoregulator function and manual setting of output percentage.

- d.i.S. (Disabled) No function available. > **Default.**
- t.H.E.r. (Thermoregulator) Enables simple thermoregulator function.
- M.A.n. (Manual) Enables manual mode.
- t.H.M.A. (Thermoregulator and Manual) Enables both simple thermoregulator and manual function.

33 H.L.d.F. Hold Function

Enables "Hold" function; allows to hold the cycle and modify setpoint by keyboard. The same function **NOT** have to be enabled on Parameter 27 d.C.t. i.

- d.i.S. (Disabled) "Hold" function disabled. > **Default.**
- E.n. (Enabled) "Hold" function enabled.

34 c.Y.A.u. Cycles Available

Selects number of available cycles.

1..15 cycles. > **Default: 15.**

35 **b.P.r.c.** Block Programming Cycles

Selects number of cycles that the user cannot modify, to avoid wrong programming. Ex.: selecting 3 the programming of first 3 cycles is locked.

0..15 locked cycles. > **Default:** 0.

36 **U.E.S.E.** Waiting Time Step End

Selects time for step end waiting in hh.mm.

00.00 Step end waiting excluded

00.01..24.00 hh.mm. > **Default:** 01.00.

37 **P.G.S.E.** Max. Gap Step End

Selects max. gap for step end waiting activation. When the difference between setpoint and process is lower than this parameter, controller switch to the next step (also without waiting time programmed into parameter 36 **U.E.S.E.**

0..200 [digit²] (degrees.tenths for temperature sensors). > **Default:** 5.

38 **r.i.c.y.** Recovery Interrupted Cycle

Enables interrupted cycle recovery function.

0 Cycle recovery disabled

1 Cycle recovery enabled with automatic gradient > **Default.**

2..9999 [digit²]. Select recovery gradient (rising).

43 **U.V.L.E.** Valve Time

Time for open/close servo-valve (value declared by servo-valve manufacturer). Not allowed for feedback valves (potentiometer).

0..300 seconds. > **Default:** 60.

45 **AL.1** Alarm 1

Alarm 1 selection.

d.i.S (Disabled). > **Default.**

A.AL (Absolute Alarm). Absolute Alarm, referring to the process.

b.AL (Band Alarm). Command setpoint $\pm$ band.

H.d.AL (High Deviation Alarm). Command setpoint + deviation.

L.d.AL (Low Deviation Alarm). Command setpoint - deviation.

A.c.S.A. (Absolute Command Setpoint Alarm). Referring to the setpoint.

S.t.AL (Start Alarm). Active in **RUN**.

E.n.d.AL (End Alarm). Active at cycle end.

A.o.r.S. (Auxiliary Output Related to the Step). ON/OFF at each step.

A.o.r.AL (Auxiliary Output Rising Maintenance). Auxiliary output active for rising and holding steps.

A.o.FA. (Auxiliary Output Falling). Auxiliary output active for falling steps.

c.o.o.L (Cooling). Actuator output for cooling during double loop functioning.

A.AL.r. (Absolute Alarm active in **RUN**).

S.A.o.P. (Start Alarm Open). Works as the alarm active in start (S.t.AL), but it opens in case of open door (digital input selected as o.P.E.n).

46 **A.I.S.O. Alarm 1 State Output**

Selects contact type for alarm 1 output.

n.o. (Normally Open). > **Default.**

n.c. (Normally Closed).

47 **A.I.E.H. Alarm 1 Threshold**

Selects setpoint value for alarm 1.

-999..+9999 [digit²]. > **Default: 0**

48 **A.I.HY Alarm 1 Hysteresis**

Selects hysteresis for alarm 1.

-999..+999 [digit²] (degrees.tenths for temperature sensors). > **Default: 1.0**

49 **A.I.S.E. Alarm 1 State Error**

Contact status for alarm 1 output in case of error.

o.c. (Open Contact) > **Default**

c.c. (Contact closed)

50 **A.I.L.d. Alarm 1 Led**

Defines led **A1** status corresponding to relevant contact.

o.c. (Open Contact)

c.c. (Contact closed) > **Default**

51 **A.I.A.E. Alarm 1 Action Type**

Type: Defines alarm 1 action type on operating cycle.

n.o.A.c. (No Action). Changes only output related to the alarm > **Default.**

E.c.Y.S. (End Cycle Signal). Cycle ends (STOP) with acoustic and visual signalling. Changes output related to the alarm, buzzer sounds and on display flashes **AL**, until pressing OK.

A.u.S.i. (Audible Signal). Only acoustic signalling: buzzer sounds.

52 **AL 2 Alarm 2**

Alarm 2 selection.

d.i.S. (Disabled). > **Default.**

A. AL. (Absolute Alarm). Referring to the process.

b. AL. (Band Alarm). Command setpoint $\pm$ band.

H.d.AL. (High Deviation Alarm). Command setpoint + deviation

L.d.AL. (Low Deviation Alarm). Command setpoint - deviation

A.c.S.A. (Absolute Command Setpoint Alarm). Referring to the setpoint.

S.t.AL. (Start Alarm). Active in **RUN**.

E.n.d.AL. (End Alarm). Active at cycle end.

A.o.r.S. (Auxiliary Output Related to the Step). ON/OFF at each step.

A.o.r.M. (Auxiliary Output Rising Maintenance). Auxiliary output active for rising and holding steps.

- A.o.FA.* (Auxiliary Output Falling). Auxiliary output active for falling.
- cool* (Cooling). Actuator output for cooling during double loop functioning.
- AA.L.r.* (Absolute Alarm active in **RUN**).
- SA.oP.* (Start Alarm Open). Works as the alarm active in start (*St.AL.*), but it opens in case of open door (digital input selected as *oPEN*).

53 *A.2.5.o.* Alarm 2 State Output

Selects contact type for alarm 2 output.

- n.o.* (Normally Open). > **Default**.
- n.c.* (Normally Closed).

54 *A.2.tH.* Alarm 2 Threshold

Selects setpoint value for alarm 2.

-999..+9999 [digit²] (degrees for temperature sensors). > **Default**: 0.

55 *A.2.HY.* Alarm 2 Hysteresis

Selects hysteresis for alarm 2.

-999..+999 [digit²] (degrees.tenths for temperature sensors). > **Default**: 1.0.

56 *A.2.5.E.* Alarm 2 State Error

Contact status for alarm 2 output in case of error.

- o.c.* (Open Contact) > **Default**
- c.c.* (Contact closed)

57 *A.2.Ld.* Alarm 2 Led

Defines led **A2** status corresponding to relevant contact.

- o.c.* (Open Contact)
- c.c.* (Contact closed) > **Default**

58 *A.2.A.t.* Alarm 2 Action Type

Defines alarm 2 action type on operating cycle.

- n.o.A.c.* (No Action). Changes only output related to the alarm. > **Default**.
- E.c.Y.S.* (End Cycle Signal). Cycle ends (STOP) with acoustic and visual signalling. Changes output related to the alarm, buzzer sounds and on display flashes *AL. 2* until pressing OK.
- Au.S.i.* (Audible Signal). Only acoustic signalling: buzzer sounds.

59 **AL.3 Alarm 3**

Alarm 3 selection

d.S. (Disabled). > **Default.**

A.AL. (Absolute Alarm). Referring to the process.

b.AL. (Band Alarm). Command setpoint $\pm$ band.

H.d.AL. (High Deviation Alarm). Command setpoint + deviation.

L.d.AL. (Low Deviation Alarm). Command setpoint - deviation.

A.c.S.A. (Absolute Command Setpoint Alarm). Referring to the setpoint.

St.AL. (Start Alarm). Active in **RUN**.

End.A. (End Alarm). Active at cycle end.

A.o.r.S. (Auxiliary Output Related to the Step). ON/OFF at each step.

A.o.r.A. (Auxiliary Output Rising Maintenance). Auxiliary output active for rising and holding steps

A.o.FA. (Auxiliary Output Falling). Auxiliary output active for falling steps.

cool (Cooling). Actuator output for cooling during double loop functioning.

A.AL.r. (Absolute Alarm active in **RUN**).

S.A.o.P. (Start Alarm Open). Works as the alarm active in start (**St.AL.**), but it opens in case of open door (digital input selected as **oPEN**).

60 **A.3.S.o. Alarm 3 State Output**

Selects contact type for alarm 3 output.

n.o. (Normally Open). > **Default.**

n.c. (Normally Closed).

61 **A.3.tH. Alarm 3 Threshold**

Selects setpoint value for alarm 3.

-999..+9999 [digit²] (degrees for temperature sensors). > **Default: 0.**

62 **A.3.HY. Alarm 3 Hysteresis**

Selects hysteresis for alarm 3.

-999..+999 [digit¹] (degrees.tenths for temperature sensors). > **Default: 1.0.**

63 **A.3.S.E. Alarm 3 State Error**

Contact status for alarm 3 output in case of error.

o.c. (Open Contact) > **Default**

c.c. (Contact closed)

64 **A.3.Ld. Alarm 3 Led**

Defines led **A3** status corresponding to relevant contact.

o.c. (Open Contact)

c.c. (Contact closed) > **Default**

65 **A.L.A.L. Alarm 3 Action Type**

Defines alarm 3 action type on operating cycle.

no.A.L. (No Action). Changes only output related to the alarm. > **Default.**

E.c.Y.S. (End Cycle Signal). Cycle ends (STOP) with acoustic and visual signalling. Changes output related to the alarm, buzzer sounds and on display flashes **AL. 3**, until pressing OK.

A.L.S.I. (Audible Signal). Only acoustic signalling: buzzer sounds.

73 **COO.F. Cooling Fluid**

Defines cooling fluid type.

A.I.R. > **Default**

Oil

H₂O

74 **P.b.M. Proportional Band Multiplier**

1.00..5.00. > **Default: 1.00.**

75 **OL.D.B. Overlap/Dead Band**

-20.0%..50.0%. > **Default: 0.0%.**

76 **CO.C.T. Cooling Cycle Time**

1..300 seconds. > **Default: 10s.**

77 **REN.S. Remote Setpoint**

Selects remote setpoint mode, through serial communication.

dis. (Disabled). Controller operates autonomously. > **Default.**

SLAVE (Slave). Controller is a slave normally in STOP: goes in **RUN** when, on master device connected to the serial, a cycle is started.

MASTER (Master). Controller transmits the setpoint to all controllers connected to the serial and set as slave.

78 **bd.r.t. Baud Rate**

Selects baud rate for serial communication.

4.8 k 4800 bit/s

9.6 k 9600 bit/s **38.4 k** 38400 bit/s

19.2 k 19200 bit/s > **Default** **57.6 k** 57600 bit/s

28.8 k 28800 bit/s **115.2 k** 115200 bit/s

79 **SE.P.S. Serial Parameters Setting**

Selects data format for serial communication.

8.n.1 8 data bits, no parity, 1 stop bit. > **Default.**

8.o.1 8 data bits, odd parity, 1 stop bit.

8.E.1 8 data bits, even parity, 1 stop bit.

80 *SLAd*. Slave Address

Selects slave address for serial communication.

1..254 Address for slave functioning. > **Default:** 254.

81 *SEdE*. Serial Delay

Select serial delay.

0..100 ms. > **Default:** 20ms.

82 *cFLt*. Conversion Filter

Adc filter: number of means on analogue-digital conversion.

1..15 samplings > **Default:** 10.

83 *u.FLt*. Visualization Filter

d iS. (Disabled)

PtCH (Pitchfork filter) > **Default.**

F i.or. (First Order)

F.or.P. (First Order with Pitchfork)

2. *S.n*. (2 Samples Mean)

3. *S.n*. (3 Samples Mean)

4. *S.n*. (4 Samples Mean)

5. *S.n*. (5 Samples Mean)

6. *S.n*. (6 Samples Mean)

7. *S.n*. (7 Samples Mean)

8. *S.n*. (8 Samples Mean)

9. *S.n*. (9 Samples Mean)

10. *S.n*. (10 Samples Mean)

84 *rEtE*. Retransmission

Retransmission for analogue output. Parameters 86 and 87 define upper/lower limit of scale

d iS. (Disabled). > **Default.**

c.SP.u. (Command Setpoint) Retransmit the command setpoint.

Pro. (Process) Retransmit the process.

85 *rEtE.t*. Retransmission Type

Select retransmission signal type.

0-10 (0..10V)

0-20 (0..20mA)

4-20 (4..20mA) > **Default.**

86 *Lo.L.r*. Lower Limit Retransmission

Lower limit analogue output range.

-999..+9999 [digit²] (degrees.tenths for temperature sensors). > **Default:** 0.

87 **U.P.L.R. Upper Limit Retransmission**

Upper limit analogue output range.

-999..+9999 [digit²] (degrees.tenths for temperature sensors).

> **Default:** 1000.

88 **P.U.r. Power**

This parameter defines the power of the heating element managed by the controller. If the selected value is different from 0.0, pressing "**OK**" at the end of the cycle, it is possible to visualize the employed energy expressed in kWh. It does not work with valve control.

0.0..+999.9 kWh

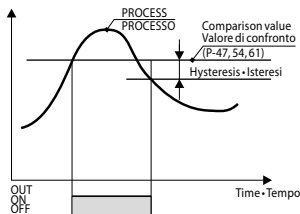
> **Default:** 0.0

13 Alarm intervention modes

ATR621 has the possibility to program up to 3 alarms.

Into the following table all intervention modes are showed.

13.a Absolute alarm

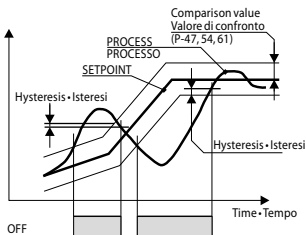


Alarm can be:

- Active over
- Active under

In the figure it is active over.

13.b Band alarm (setpoint-process)



Alarm can be:

- Active outside
- Active inside

In the figure it is active outside.

² The display of the decimal point depends on the setting of parameters **SEn** and **d.P.**

[illegible]

Table of configuration parameters

1	c.out	Command Output	26
2	SEn.	Sensor	26
3	d.P.	Decimal Point	27
4	LoL.i.	Lower Linear Input	27
5	uPL.i.	Upper Linear Input	27
6	o.cAL.	Offset Calibration	27
7	G.cAL.	Gain Calibration	27
8	LoL.S.	Lower Limit Setpoint	27
9	uPL.S.	Upper Limit Setpoint	27
10	dEGr.	Degree	27
11	tunE	Tune	28
12	S.d.tu.	Setpoint Deviation Tune	28
13	Π.G.tu.	Max Gap Tune (password 5678)	28
14	Πn.P.b.	Minimum Proportional Band (password 5678)	28
15	ΠP.P.b.	Maximum Proportional Band (password 5678)	28
16	Πn.i.t.	Minimum Integral Time (password 5678)	28
18	Act.t.	Command Action Type	28
19	c.HY.	Command Hysteresis	28
20	P.b.	Proportional Band	28
21	t.i.	Integral Time	29
22	t.d.	Derivative Time	29
23	t.c.	Cycle Time	29
24	LL.o.P.	Lower Limit Output Percentage	29
25	uLo.P.	Upper Limit Output Percentage	29
26	c.S.E.	Command State Error	29
27	dGE.i.	Digital Input	29
28	d.i.c.t.	Digital Input Contact Type:	30
29	u.i.d.2	Visualization Display 2	30
30	dE.St.	Delayed Start	30
31	S.SPu	Starting Setpoint	30
32	SP.Fu.	Special Functions	30
33	Hld.F.	Hold Function	30
34	cYAv.	Cycles Available	30
35	b.Pr.c.	Block Programming Cycles	31
36	U.t.S.E.	Waiting Time Step End	31
37	Π.G.S.E.	Max. Gap Step End	31
38	r.i.cY.	Recovery Interrupted Cycle	31
43	VAL.t.	Valve Time	31
45	AL.1	Alarm 1	31
46	AL.S.o.	Alarm 1 State Output	32
47	AL.t.H.	Alarm 1 Threshold	32

48	A.1.HY	Alarm 1 Hysteresis	32
49	A.1.S.E.	Alarm 1 State Error	32
50	A.1.Ld.	Alarm 1 Led	32
51	A.1.A.t.	Alarm 1 Action Type	32
52	AL_2	Alarm 2	32
53	A.2.S.o.	Alarm 2 State Output	33
54	A.2.tH.	Alarm 2 Threshold	33
55	A.2.HY.	Alarm 2 Hysteresis	33
56	A.2.S.E.	Alarm 2 State Error	33
57	A.2.Ld.	Alarm 2 Led	33
58	A.2.A.t.	Alarm 2 Action Type	33
59	AL_3	Alarm 3	34
60	A.3.S.o.	Alarm 3 State Output	34
61	A.3.tH.	Alarm 3 Threshold	34
62	A.3.HY.	Alarm 3 Hysteresis	34
63	A.3.S.E.	Alarm 3 State Error	34
64	A.3.Ld.	Alarm 3 Led	34
65	A.3.A.t.	Alarm 3 Action Type	35
73	coo.F.	Cooling Fluid	35
74	P.b.Π.	Proportional Band Multiplier	35
75	ou.d.b.	Overlap/Dead Band	35
76	co.c.t.	Cooling Cycle Time	35
77	rEN.S.	Remote Setpoint	35
78	bd.rt.	Baud Rate	35
79	SE.P.S.	Serial Parameters Setting	35
80	SL.Ad.	Slave Address	36
81	SE.dE.	Serial Delay	36
82	c.FLt.	Conversion Filter	36
83	u.FLt.	Visualization Filter	36
84	rEt.r.	Retransmission	36
85	rEt.Y.	Retransmission Type	36
86	Lo.L.r.	Lower Limit Retransmission	36
87	uPL.r.	Upper Limit Retransmission	37
88	PUr.	Power	37



Read carefully the safety guidelines and programming instructions contained in this manual before using/connecting the device.

Prima di utilizzare il dispositivo leggere con attenzione le informazioni di sicurezza e settaggio contenute in questo manuale.



RoHS 
Compliant



PIXSYS s.r.l.

www.pixsys.net

sales@pixsys.net - support@pixsys.net

online assistance: <http://forum.pixsys.net>



2300.10.148-RevC

Software Rev. 1.08

090117